Outstanding Hurdles

Mini's Growth



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Mini's Growth

Outstanding Hurdles

- Missing R++ functionality
 - rtmin, wobble & chuck
- Library subdivision
- Allow EnergyMethods outside core/
- Documentation
- Selection Syntax
- Protocol Integration
- Testing

API Improvement

- Theorem: The command line is a poor place to script
- Proof: By *Reductio ad absurdum.* Assume the comamnd line is a good place to script,





for i = 1:nstruct dock L to A for j = 1:10 dock B to AL design ALB interface minimize ALB jumps + sc



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Assumption: the command line is a good place to script. Two different docking runs (AL, BAL) read the same flags ... The command line is a poor place to script



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Alt#1: B is fixed in sequence Alt#3: L is designable Alt#5: Favor native seq for A Alt#7: Filter each i, each j Alt#2: A has flexible loops Alt#4: A's loop lengths can vary Alt#6: minimize N designs



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Complications:

- Kinematic topology changes
- Sequence length might change
- Score function might change



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API Example: MatcherTask

- match.cc only reads the command line
- initialize_from_command_line()
 - Reads all matcher flags
 - Does not have to be called
 - Can be called and overwritten (not commutative)
- Every flag has a corresponding data member, accessor, and mutator
- Task is passed around to many different classes during Matcher initialization

- Unit Tests Rock
 - Will catch bugs integration tests miss
 - Guarantee code is working correctly
 - No wasted production runs with buggy code
 - Speed code development
 - Find bugs early
 - Pinpoints bugs!
- 180 core/ tests, 130 protocols/ tests, need 10x more

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- Two challenges in writing unit tests
 - 1. Adding a new test to the test framework
 - Insultingly easy
 - 2. Deciding under what conditions your code is operating correctly
 - Hard, but essential

• E.g. test/protocols/match/BumpGrid.cxxtest.hh

```
class BumpGridTests : public CxxTest::TestSuite {
  private:
    numeric::geometry::BoundingBox< core::Vector > bb_, bb2_;
```

```
public:
    void setUp() {
        /// next slide
    }
    void test_bool3D_or_overlap() {
        /// slide after next
    }
};
```

```
// Shared initialization goes here.
void setUp() {
    core_init();
    lower_corner_ = core::Vector( 1.0, 1.0, 0.0 );
    upper_corner_ = core::Vector( 10.0, 11.0, 12.0 );
    bb_ = numeric::geometry::BoundingBox< core::Vector >( lower_corner_, upper_corner_ );
    lower_corner2_ = core::Vector( 4.0, -1.0, 4.0 );
    upper_corner2_ = core::Vector( 10.0, 15.0, 12.0 );
    bb2_ = numeric::geometry::BoundingBox< core::Vector >( lower_corner2_, upper_corner2_ );
```

```
}
```

void test_bool3D_or_overlap() {
 Bool3DGrid bool3d1, bool3d2;
 bool3d1.set_bounding_box(bb_);
 bool3d2.set_bounding_box(bb2_);

```
TS_ASSERT( bool3d2.actual_bb().lower().x() == 4.0 );
TS_ASSERT( bool3d2.actual_bb().lower().y() == -1.0 );
TS_ASSERT( bool3d2.actual_bb().lower().z() == 4.0 );
```

TS_ASSERT(bool3d2.actual_bb().upper().x() == 12.0); TS_ASSERT(bool3d2.actual_bb().upper().y() == 15.0); TS_ASSERT(bool3d2.actual_bb().upper().z() == 12.0);

```
core::Vector center( 7.5, 5.5, 8.5 );
core::Vector contained( 8.5, 5.5, 8.5 );
core::Vector edge_case( 9.5, 5.5, 8.5 );
```

```
bool3d2.or_by_sphere_conservative( center, 2 );
```

```
TS_ASSERT( bool3d2.occupied( center ) );
TS_ASSERT( bool3d2.occupied( contained ) );
TS_ASSERT( !bool3d2.occupied( edge_case ) );
TS_ASSERT( !bool3d1.occupied( center ) );
TS_ASSERT( !bool3d1.occupied( contained ) );
TS_ASSERT( !bool3d1.occupied( edge_case ) );
```

```
bool3d1.or_with( bool3d2 );
TS_ASSERT( bool3d1.occupied( center ) );
TS_ASSERT( bool3d1.occupied( contained ) );
TS_ASSERT( !bool3d1.occupied( edge_case ) );
```

}

- Development workflow
 - Sketch out your classes
 - Starting with central classes
 - Start implementing class C
 - Write part of class C
 - Compile class C
 - Write a unit test, run, debug
 - Repeat
 - Run unit tests for all classes
- Development is faster & afterwards, tests persist!

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